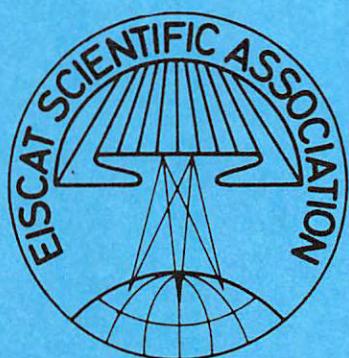


D.



EISCAT  
TECHNICAL  
NOTE

A Mesospheric Experiment:  
Measurement Scheme  
and Program Implementation

by  
W. Kofman

KIRUNA  
Sweden

A MESOSPHERIC EXPERIMENT : MEASUREMENT SCHEME AND  
PROGRAM IMPLEMENTATION

W. Kofman

EISCAT Scientific Association  
S-981 27 Kiruna Sweden  
March 1982  
EISCAT Technical Note 82/35  
Printed in Sweden  
ISSN 0349-2710

## INTRODUCTION

This technical note describes the programs proposed for performing a mesospheric experiment. We show the measurement schemes selected and the actual program implementation; and the correlator and radar controller programs.

The program at the EROS level has not been developed yet; this will be done by the EISCAT staff in the near future.

### 1 - MEASUREMENT SCHEME

Groups from different countries proposed mesospheric experiments which were in general very similar though there were minor differences as to the need to measure clutter.

Mesospheric measurements need a good height resolution (~2 km). For that reason we have to use very short transmission pulses (~20  $\mu$ sec) or Barker-coded pulses. The theoretical instantaneous signal-to-noise ratio is very low ( $10^{-3} - 10^{-4}$  for 20  $\mu$ sec pulses) and therefore the integration time will be very long. The theoretical mesospheric spectrum will be very narrow and so we cannot use the ordinary multi-pulse mode to measure it. Instead we propose to calculate the correlation function from pulse to pulse. Figure 1 explains this technique.

The transmitter sends the first pulse at time  $t = 0$  and the receiver takes successive samples from different altitudes  $s_{1,A_1}, s_{1,A_2}, \dots, s_{1,A_n}$  where the subscript 1 refers to the first pulse, and the subscript  $A_i$  refers to the i'th altitude. The second transmission occurs after a few milliseconds and the receiver is opened to take new data  $s_{2,A_1}, s_{2,A_2}, \dots, s_{2,A_n}$ .

After G pulses are transmitted the buffer memory will be commuted and the correlator will calculate the correlation functions for each altitude :-

$$\rho_{A_i}^P(k) = \sum_{j=1}^{G-k} s_{j,A_i} s_{j+k,A_i} \quad 0 \leq k \leq G-1$$

The different correlation functions for different blocks of data will be averaged to give an estimate of the desired correlation function :-

$$\langle \rho_{A_i}^P(k) \rangle = \frac{1}{P} \sum_{p=1}^P \rho_{A_i}^P(k)$$

The average of this estimate is then given by :-

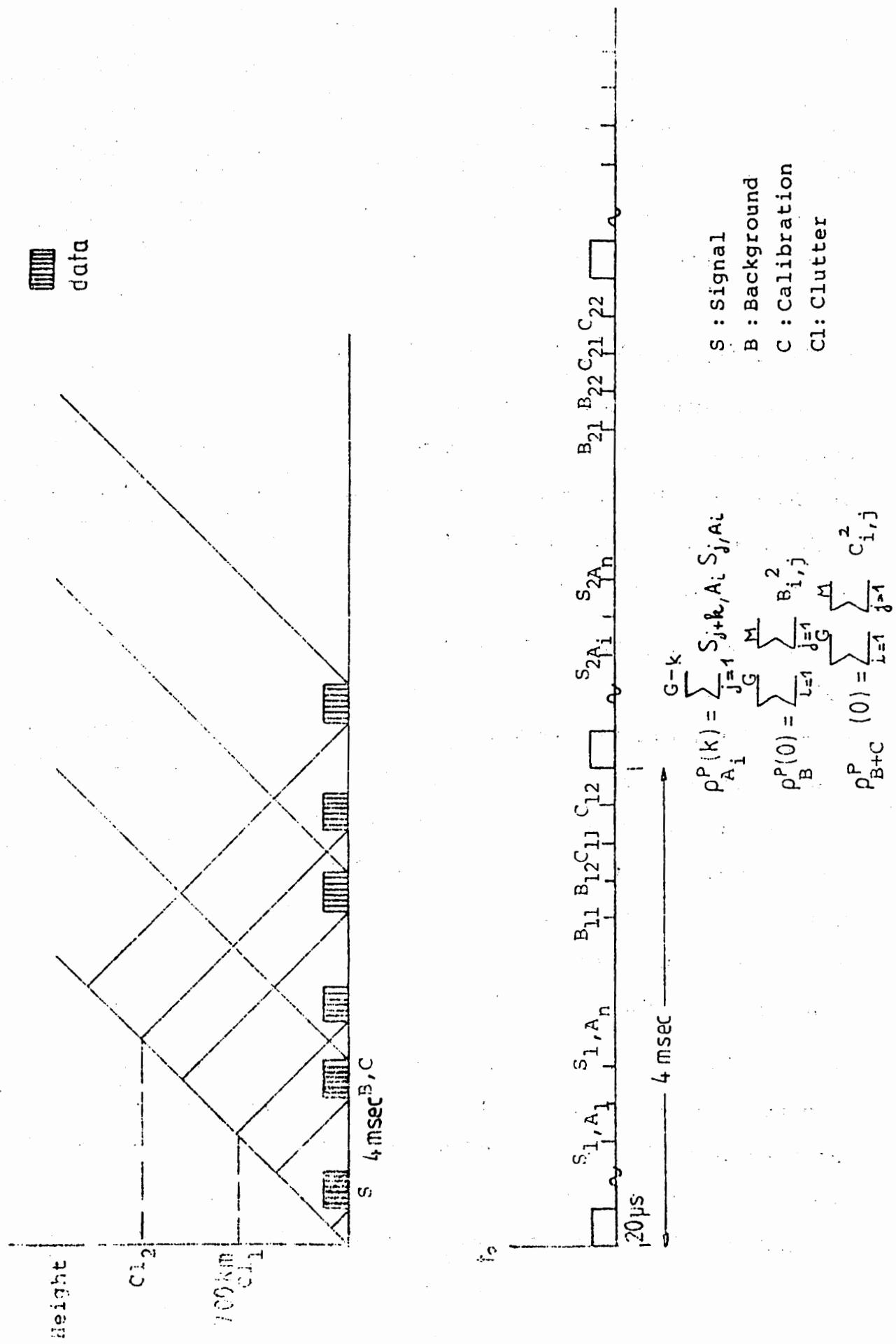
$$\langle \langle \rho_{A_i}^P(k) \rangle \rangle = \rho_{A_i}^P(0) + P_B \delta(k) + P_{Cl} \delta(k) \quad \delta(k) = 1 \text{ for } k=0 \\ = 0 \text{ for } k \neq 0$$

where  $P_B$  is the power of the background noise and  $P_{Cl}$  the power of the clutter;  $\rho_{A_i}^P(k)$  represents the correlation function of the medium so that  $\rho_{A_i}^P(0)$  represents the power in the ionic and electronic part of the analysed bandwidth and  $\rho_{A_i}^P(k)$  for  $k \neq 0$  the correlation function corresponding to the ionic part of the spectrum.

The term due to background noise only perturbs the first point in the correlation function as the bandwidth of the noise is much larger than the bandwidth of the measured signal (N.B. a good height resolution requires a short pulse and hence a wide receiver bandwidth). The third term is due to clutter received from greater altitudes, as shown in Fig. 1.

The first clutter-to-noise ratio,  $Cl_1/B$ , is  $\sim 10^{-2}$  for the typical experiment using a 4 msec pulse-repetition-rate and a 20  $\mu$ sec pulse. The second clutter-to-noise ratio,  $Cl_2/B$ , is  $\sim 10^{-7} - 10^{-9}$ . As the typical signal-to-noise ratio is  $10^{-3} - 10^{-4}$  it is only necessary to remove clutter from the first height. Indeed, as the ionic part of the first point in the correlation function can easily be

FIGURE 1



extrapolated from the other lags, but in order to normalise the data correctly it is necessary to measure the first point. At this stage it is not certain which method is better and so the proposed scheme of measurement allows the correlation function to be determined with or without the removal of clutter. The same correlator program can be used in both cases and only the radar controller program need be changed.

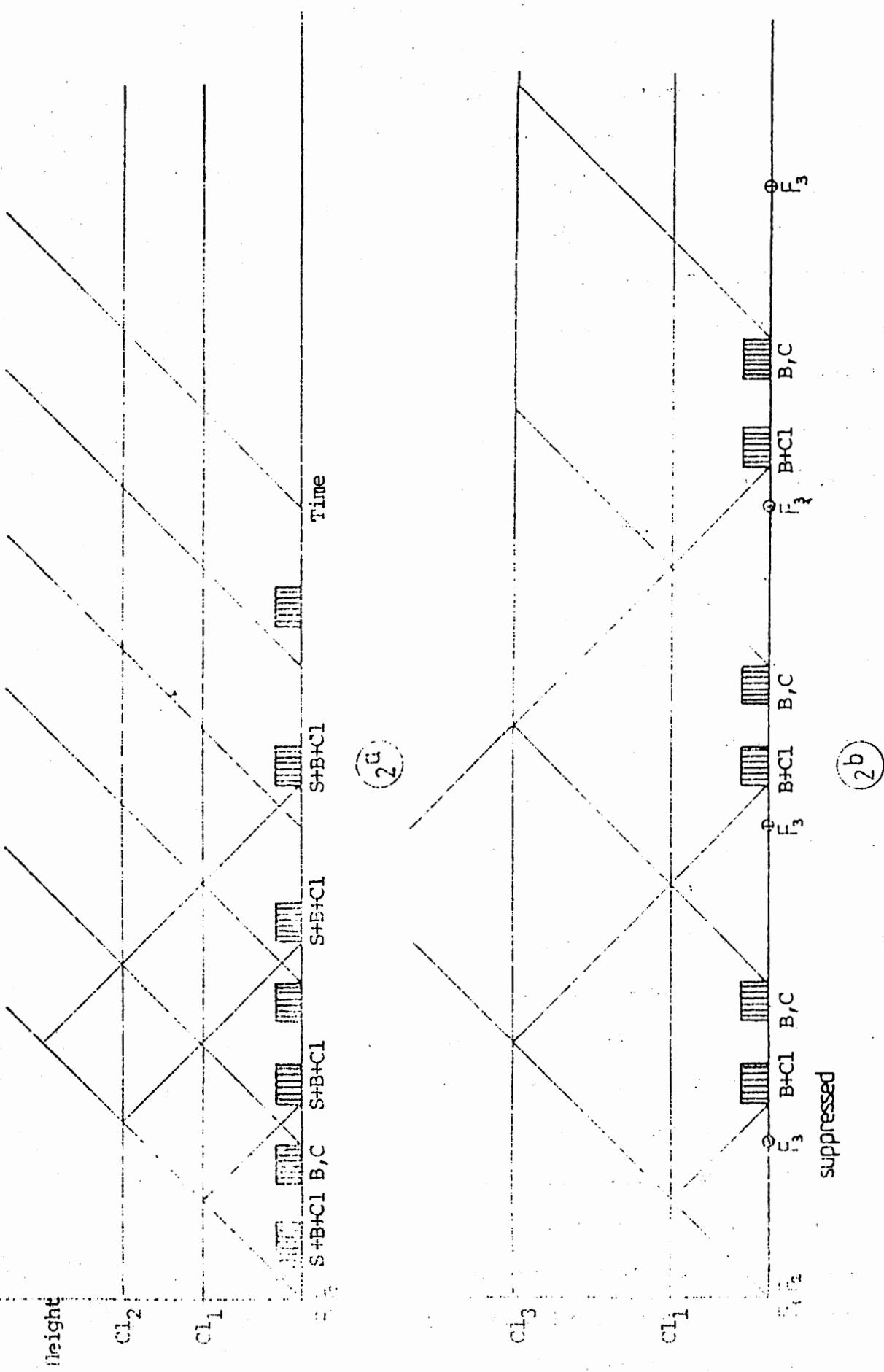
a) The pulse scheme without clutter measurement

The measurement scheme is plotted in Fig. 2. The pulse-repetition-period will be typically 4 msec which gives an available bandwidth of 250 Hz for the measured spectrum, as the receiver provides both quadrature components. The spectral resolution depends on the number of lags measured and will probably be a few Hz.

For a 4 msec repetition period, the first clutter comes from a height of 600 - 700 km. Calibration and background noise are measured immediately before the next pulse is transmitted. If clutter is neglected these measurements of the calibration signal and the background noise allow us to normalise the total scattered power correctly in order to measure the component due to the electrons. When clutter is too strong, however, extrapolation must be used to estimate the first point of the correlation function for the ionic part of the spectrum.

To make full use of the capabilities of the transmitter at least two frequencies will be used, and the pulses will probably be Barker-coded. The Barker codes ameliorate the instantaneous signal-to-noise ratio for the same height resolution as before, but the secondary lobe effect can be a serious problem. Possibly the use of the complementary codes will be necessary.

FIGURE 2



$2^a$  : we measure signal+background+clutter; background+clutter; and background+calibration+clutter.

$2^b$  : we measure background+clutter; background; and background+calibration.

b) The pulse scheme with clutter measurement

We propose a simple scheme of measurement which permits us to obtain every other order of clutter (i.e.  $C_{l_1}, C_{l_3}, C_{l_5} \dots$ ). For an initial period of, say, 10 seconds the previous scheme of measurement is used; for the next 10 seconds every alternative pulse is suppressed so that the new mode will measure the background noise plus the clutter from heights 1, 3, 5 etc. (see Fig. 2). In this scheme a third transmitter frequency is used so that the clutter measurements can correspond exactly to the mesospheric signal measurements.

In this scheme the time resolutions is worse by a factor of two. In order to change from one scheme to the other it is only necessary to reload the TARLAN program as the correlator program is the same in both cases.

2 - PROGRAM DESCRIPTION

a) Pulse generation (TARLAN)

The radar controller (RC) which controls the timing of the transmitted and received pulses does not allow loops inside a program. At the end of each cycle of measurement the RC sends a "start-compute" signal to the correlator and restarts a new cycle. At this stage the two halves of the buffer memory are commuted. This mode is not really suitable for an experiment making pulse-to-pulse correlation measurements because we have to fill one half of the buffer memory with many samples corresponding to different pulses before starting the calculation and commuting the buffer memory, and so we should not send the "start-compute" order before filling one half of the buffer memory. This implies that the scheme is limited either by the size of the buffer memory (4K for each half) or by the size of the PC (4K) which limits the number of

instructions that we can program.

From the statistical point of view it is desirable to have the number of samples much larger than the number of calculated lags. This is due to the fact that it is not possible to calculate the correlation between samples in the two halves of the buffer memory. The equations describing the limitations of the buffer and result memory are :-

$$(n_A + n_B + n_C) \times n_F \times G = 4096$$

$$n_L \times n_A \times n_F + 2n_F = 2048$$

where  $n_A$  are the number of samples corresponding to different altitudes

$n_B$  are the number of samples corresponding to the background measurements

$n_C$  are the number of samples corresponding to the calibration measurements

$n_F$  are the number of frequencies

$n_G$  are the number of pulses transmitted in each cycle and

$n_L$  are the number of lags measured.

A program generating the TARLAN instructions for a typical experiment is shown in Annex 1. The pulses are transmitted on two frequencies, and two receiver channels take the data separately for 8 signal, 4 background and 4 calibration samples. This program gives almost optimal filling of RC by TARLAN instructions and of the buffer memory by samples.

In this case 200 pulse-repetition-periods are used to produce each correlation function. The long pulse on F4 will be received in Kiruna and Sodankylä to measure both the ionic and electronic parts of the spectrum.

b) Correlator program

i) Program without coherent integration

This program calculates the correlation function for each altitude, the power for background and calibration (Fig. 2) adding the power for all samples (see Annex 2). The registers of the APB, APM processors must be defined in the main program in EROS.

	<u>Register name</u>	<u>Register address</u>	<u>Parameters</u>
APB	RS (15)	16,15	No. of pulses transmitted - 1
APB	RS (14)	16,14	No. of range gates - 1 (signal)
APB	RS (13)	16,13	No. of lags - 1 (signal)
APB	RS (12)	16,12	- (RS (15) x RS (11) - 1)
APB	RS (11)	16,11	No. of altitudes + no. of background samples + no. of calibration samples.
APB	RS (8)	16,8	No. of background samples - 1
APB	RS (7)	16,7	No. of calibration samples - 1
APB	RS (6)	16,6	No. of frequencies
APB	RS (5)	16,5	1
APB	RS (3)	16,3	Address increment between the end of the data corresponding to one frequency and the beginning of the data corresponding to another.
APM	RS (15)	17,15	Range gate increment (= no. of lags for each correlation function)
APM	RS (14)	17,14	1
APM	RS (0)	17,0	Increment for transfer = 1

I register APB = no. of words to transfer + 1.

ii) Program with coherent integration (developed by Regi Gras)

The correlation function varies slowly in the D region. When the temporal separation between samples from the same altitude is much shorter than the correlation time, we can use coherent integration. For instance, for a spectrum of 10 Hz bandwidth the correlation time is about 0.1 seconds and for this we can always add two successive samples at a 4 msec separation. The amplitude of these two samples is almost the same due to the high correlation and so the signal-to-noise ratio is improved by a factor of 1.41. This technique can be very useful for mesospheric measurements.

For instance let  $s_1, s_2, \dots, s_G$  be the samples for one altitude; then the program calculates the correlation function :-

$$\rho(k) = \sum_{i=1}^P a_i a_{i+k}^* \quad \text{where } a_i = \sum_{j=1}^H s_{i+j}$$

where H is the number of samples summed coherently. This program calculates the background and calibration powers as in the previous case (see Annex 3)

---

Acknowledgements

I wish to thank Terrance Ho, Bård Törustad and Regi Gras for the help in program preparation.

---

ANNEX 1

Program to generate the TARLAN instructions for 200 p.r.p.

OUTPUT(10) 'TROMSO'

C NUMBER OF SAMPLES FOR ONE SCAN EQUAL NUMBER OF REPETITION OF THIS  
 C PROGRAM. THE LIMITATION BY RADAR CONTR. MEMORY ONLY 4096 WORDS  
 C NUMBER OF SAMPLES(MAX)=200, NOT OPTIMAL USE OF DATA  
 C OPTIMAL USE OF DATA IS NUMBER OF SAMPLES/NUMBER OF LAGS DUE TO  
 C SPLIT INTO TWO PARTS OF BUFFER MEMORY, THIS LIMITATION ONLY FOR  
 C MESOSPHERIC EXPERIMENT.  
 C POSSIBILITY TO USE THE SECOND COUNTER IN RC TO AVOID THE  
 C REPETITION. HOW TO DO IT?  
 C 4000=TIME BETWEEN TRANSMISSIONS, SAMPLING RATE FOR CORRELATION MEAS

:DO FOR I=1,200

OUTPUT(10) 'SETTCR', (I-1)\*4000

OUTPUT(10) 'AT 1 TRANS'

OUTPUT(10) 'AT 2 SYSON'

OUTPUT(10) 'AT 5 HVON'

OUTPUT(10) 'AT 35 F4'

OUTPUT(10) 'AT 635 F1'

OUTPUT(10) 'AT 655 F2'

OUTPUT(10) 'AT 675 F0FF HV0FF'

OUTPUT(10) 'AT 677 SYSOFF'

OUTPUT(10) 'AT 750 REDEV'

OUTPUT(10) 'AT 1035 CH1'

OUTPUT(10) 'AT 1055 CH2'

C SAMPLING RATE=20USEC ON CH1 AND CH2

C DATA START ON 60 KM WITH 3.0 KM RESOLUTION

C TO HAVE EXACTE NUMBER OF SAMPLES

C TOFF=TON+(N-1)\*TSAMP+TSAMPL/2

OUTPUT(10) 'AT 1185 CH1OFF'

OUTPUT(10) 'AT 1205 CH2OFF'

OUTPUT(10) 'AT 3800 CH1 CH2'

OUTPUT(10) 'AT 3870 ALLOFF'

OUTPUT(10) 'AT 3872 CAL30'

OUTPUT(10) 'AT 3922 CH1 CH2'

OUTPUT(10) 'AT 3992 ALLOFF'

OUTPUT(10) 'AT 3997 CAL0'

ENDO

OUTPUT(10) 'SETTCR', 800000

OUTPUT(10) 'AT 1 TRANS'

OUTPUT(10) 'AT 2 SYSON'

OUTPUT(10) 'AT 5 HVON'

OUTPUT(10) 'AT 35 F4'

OUTPUT(10) 'AT 635 F1'

OUTPUT(10) 'AT 655 F2'

OUTPUT(10) 'AT 675 F0FF HV0FF'

OUTPUT(10) 'AT 677 SYSOFF'

OUTPUT(10) 'AT 750 REDEV'

OUTPUT(10) 'AT 1035 CH1'

OUTPUT(10) 'AT 1055 CH2'

C SAMPLING RATE=20USEC ON CH1 AND CH2

C DATA START ON 60 KM WITH 3.0 KM RESOLUTION

C TO HAVE EXACTE NUMBER OF SAMPLES

C TOFF=TON+(N-1)\*TSAMP+TSAMPL/2

OUTPUT(10) 'AT 1185 CH1OFF'

OUTPUT(10) 'AT 1205 CH2OFF'

OUTPUT(10) 'AT 3800 CH1 CH2'

OUTPUT(10) 'AT 3870 ALLOFF'

OUTPUT(10) 'AT 3872 CAL30'

OUTPUT(10) 'AT 3922 CH1 CH2'

OUTPUT(10) 'AT 3983 STC'

OUTPUT(10) 'AT 3990 STCOFF'

OUTPUT(10) 'AT 3992 ALLOFF'

OUTPUT(10) 'AT 3994 CAL0'

OUTPUT(10) 'AT 3995 SEP'

OUTPUT(10) 'ENDI'

C INPUT(10) 'TRIMSON'  
 C NUMBER OF SAMPLES FOR ONE SCAN EQUAL NUMBER OF REPETITION OF DATA  
 C PROGRAM. THE LIMITATION BY RADAR COMPU. MEMORY ONLY 4096 WORDS.  
 C NUMBER OF SAMPLES(MAX)=200, NOT OPTIMAL USE OF DATA.  
 C OPTIONAL USE OF DATA IS NUMBER OF SAMPLES, NUMBER OF LAGS DUE TO  
 C SPLIT INTO TWO PARTS OF BUFFER MEMORY, THIS COMPUTATION ONLY FOR  
 C MESOSPHERIC EXPERIMENT.  
 C POSSIBILITY TO USE THE SECOND PRINTS IN SC. TO AVOID THE  
 C REPETITION. HOW TO DO IT?  
 C 4000=TIME BETWEEN TRANSMITS FROM SAMPLE RATE FOR CORRELATION  
 DO FOR I=1-200  
 OUTPUT(10)'SETTDR',I-1+4000  
 OUTPUT(10)'AT 1 TRANS'  
 OUTPUT(10)'AT 2 SYSON'  
 OUTPUT(10)'AT 5 HUON'  
 OUTPUT(10)'AT 35 F4'  
 OUTPUT(10)'AT 335 F1'  
 OUTPUT(10)'AT 355 F2'  
 OUTPUT(10)'AT 875 FOFF HVOFF'  
 OUTPUT(10)'AT 877 SYOFF'  
 OUTPUT(10)'AT 750 RECEIV'  
 OUTPUT(10)'AT 1035 CH1'  
 OUTPUT(10)'AT 1035 CH2'  
 C SAMPLING RATE=200SEC ON CH1 AND CH2  
 C DATA START ON 50 KM WITH 3.0 KM RESOLUTION  
 C TO HAVE EXACTE NUMBER OF SAMPLES  
 C TOFF=T0N+(N-1)\*SAMPLE\*SAMPLE/C  
 OUTPUT(10)'AT 1185 CH1OFF'  
 OUTPUT(10)'AT 1205 CH2OFF'  
 OUTPUT(10)'AT 3800 CH1 CH2'  
 OUTPUT(10)'AT 3870 ALLOFF'  
 OUTPUT(10)'AT 3872 CAL307'  
 OUTPUT(10)'AT 3902 CH1 CH2'  
 OUTPUT(10)'AT 3922 CH1 CH2'  
 OUTPUT(10)'AT 3942 CH1 CH2'  
 OUTPUT(10)'SETTDR',400000  
 OUTPUT(10)'AT 1 TRANS'  
 OUTPUT(10)'AT 2 SYSON'  
 OUTPUT(10)'AT 5 HUON'  
 OUTPUT(10)'AT 35 F4'  
 OUTPUT(10)'AT 335 F1'  
 OUTPUT(10)'AT 355 F2'  
 OUTPUT(10)'AT 875 FOFF HVOFF'  
 OUTPUT(10)'AT 877 SYOFF'  
 OUTPUT(10)'AT 750 RECEIV'  
 OUTPUT(10)'AT 1035 CH1'  
 OUTPUT(10)'AT 1035 CH2'  
 C SAMPLING RATE=200SEC ON CH1 AND CH2  
 C DATA START ON 50 KM WITH 3.0 KM RESOLUTION  
 C TO HAVE EXACTE NUMBER OF SAMPLES  
 C TOFF=T0N+(N-1)\*SAMPLE\*SAMPLE/C  
 OUTPUT(10)'AT 1185 CH1OFF'  
 OUTPUT(10)'AT 1205 CH2OFF'  
 OUTPUT(10)'AT 3800 CH1 CH2'  
 OUTPUT(10)'AT 3870 ALLOFF'  
 OUTPUT(10)'AT 3872 CAL307'  
 OUTPUT(10)'AT 3902 CH1 CH2'  
 OUTPUT(10)'AT 3922 CH1 CH2'  
 OUTPUT(10)'AT 3942 CH1 CH2'  
 OUTPUT(10)'AT 3962 CH1 CH2'  
 OUTPUT(10)'AT 3982 CH1 CH2'  
 OUTPUT(10)'AT 4002 CH1 CH2'

ANNEX 2

Pulse-to-pulse correlation (with number of lags less than number of samples) plus power measurements.

Memory Location	PRO	APB	APM
00			
01		RS (4)=RS (5)	
02			
03	Reload LCR1 ←	RS (4)	
04			
05	LC1 = LCR1		
06	Yes 	RS (4)=RS (4)-1	
07	Reload LCR1	RS (15)	
08			
09	Reload LCR2	RS (14)	
10			
11	Reload LCR3	RS (13)	
12	CALL SUB. Pulse-to-pulse		
13	Reload LCR2	RS (8)	
14	CALL POWER	Q=Q+RS (12)	Q=Q+Range gate increment
15	Reload LCR2	RS (7)	
16	CALL POWER	Q=RS (12)+Q	Q=Q+1
17	GO TO —————		
18	→	Incrementation of scan count	
19	GO TO 0 (END)		SET FF2

X X X CORRELATOR SIMULATOR X X X

PROGRAM NAME : FRENCH EXPERIMENT.

CODING (INTEGER) OF SEPARATE CORRELATOR FUNCTIONS

PROGRAM-INSTRUCTIONS DEFINED

MEM-LOC.	COND.	CODE-B	CODE-A	ABSR.	LC1	LC1A	LC2	LC3	RELOAD	R-ADDR.
0	56	0	4	0	0	0	0	0	0	0
1	56	0	4	0	0	0	0	0	0	0
2	56	0	4	0	0	0	0	0	0	0
3	56	0	4	0	0	0	0	0	1	18
4	56	0	4	0	0	0	0	0	0	0
5	56	0	4	0	2	0	0	0	0	0
6	57	5	9	18	0	0	0	0	0	0
7	56	0	4	0	0	0	0	0	1	18
8	56	0	4	0	0	0	0	0	0	0
9	56	0	4	0	0	0	0	0	1	19
10	56	0	4	0	0	0	0	0	0	0
11	56	0	4	0	0	0	0	0	1	20
12	56	0	10	20	0	0	0	0	0	0
13	56	0	4	0	0	0	0	0	1	19
14	56	0	10	40	0	0	0	0	0	0
15	56	0	3	0	0	0	0	0	1	19
16	56	0	10	45	0	0	0	0	0	0
17	56	0	3	3	0	0	0	0	0	0
18	56	0	4	0	0	0	0	0	0	0
19	56	0	4	0	0	0	0	0	0	0
20	56	0	4	0	2	0	0	3	0	0
21	61	5	4	0	0	1	0	0	1	0
22	61	5	4	0	0	1	1	0	1	0
23	61	5	4	0	0	1	1	0	1	0
24	56	0	4	0	0	0	0	0	0	0
25	57	5	9	0	0	0	0	0	0	0
26	56	1	3	0	0	0	0	0	0	0
27	56	0	4	0	0	0	0	0	0	0
28	56	0	4	0	0	0	0	0	0	0
29	56	0	4	0	0	0	0	0	0	0
30	56	0	4	0	0	0	0	0	0	0
31	56	0	4	0	0	0	0	0	0	0
32	56	0	4	0	0	0	0	0	0	20
33	56	0	4	0	0	0	0	0	0	0
34	56	0	4	0	0	0	0	0	0	0
35	56	0	4	0	0	0	0	0	0	0
36	56	0	4	0	0	0	0	0	0	0
37	56	0	4	0	0	0	0	0	0	0
38	56	0	4	0	0	0	0	0	0	0
39	56	0	4	0	0	0	0	0	0	0
40	60	0	5	0	0	0	0	0	0	0
41	56	0	4	0	0	0	0	0	0	0
42	56	0	4	0	0	0	0	0	0	0
43	56	0	4	0	0	0	0	0	0	0
44	56	0	4	0	0	0	0	0	0	0
45	56	0	4	0	0	0	0	0	0	0
46	57	5	4	50	1	0	0	0	0	0
47	57	5	4	50	1	0	0	0	0	0
48	57	5	4	50	1	0	0	0	0	0
49	56	0	4	0	0	0	0	0	0	0
50	56	0	4	0	0	0	0	0	0	0
51	56	0	1	0	0	0	0	0	0	0

MEM-LOC.	APB-INSTRUCTIONS DEFINED					
	ALU-SOURCE	ALU-FUNCTION	ALU-DESTIN.	A-ADDR.	B-ADDR.	SELECT
0	7	5	1	0	0	0
1	4	0	3	5	4	0
2	7	5	0	0	0	0
3	4	0	1	4	0	0
4	7	6	1	0	0	0
5	7	5	1	0	0	0
6	1	1	3	5	4	0
7	4	0	1	15	0	0
8	7	5	1	0	0	0
9	4	0	1	14	0	0
10	7	5	1	13	0	0
11	4	0	1	9	0	0
12	7	5	1	6	0	0
13	4	0	1	12	0	0
14	0	0	0	12	0	0
15	4	0	1	12	0	0
16	0	0	0	5	0	0
17	0	0	0	0	0	0
18	7	5	1	0	0	0
19	7	5	1	12	0	0
20	0	5	1	12	0	0
21	0	0	0	11	0	0
22	0	0	3	11	0	0
23	1	0	3	9	0	0
24	7	0	0	11	0	0
25	7	2	0	0	0	0
26	7	2	1	0	0	0
27	7	2	1	0	0	0
28	7	2	1	0	0	0
29	7	2	1	0	0	0
30	7	2	1	0	0	0
31	7	2	1	0	0	0
32	7	2	1	0	0	0
33	7	2	1	0	0	0
34	7	2	1	0	0	0
35	7	2	1	0	0	0
36	7	2	1	0	0	0
37	7	2	1	0	0	0
38	7	2	1	0	0	0
39	7	2	1	0	0	0
40	7	2	1	0	0	0
41	7	2	1	0	0	0
42	7	2	1	0	0	0
43	7	2	1	0	0	0
44	7	2	1	0	0	0
45	0	0	0	12	0	0
46	0	0	0	12	0	0
47	0	2	0	11	0	0
48	0	0	0	11	0	0
49	0	2	1	0	0	0
50	7	2	1	0	0	0
51	7	2	1	0	0	0

MEM-LOC.	APM-INSTRUCTIONS DEFINED			A-ADDR.	B-ADDR.
	ALU-SOURCE	ALU-FUNCTION	ALU-DESTIN.		
0	7	5	1	0	0
1	7		1	0	0
2	7		0	0	0
3	7		1	0	0
4	7		1	0	0
5	7		1	0	0
6	7		1	0	0
7	7		1	0	0
8	7		1	0	0
9	7		1	0	0
10	7		1	0	0
11	7		1	0	0
12	7		1	0	0
13	7		1	0	0
14	0		0	15	0
15	7	5	1	0	0
16	0	0	0	14	0
17	0	0	0	14	0
18	2	7	1	0	0
19	7	0	0	0	0
20	0	0	1	15	0
21	0	0	0	15	0
22	0	0	3	14	0
23	0	1	3	14	0
24	2	2	1	0	0
25	2	2	1	0	0
26	2	2	1	0	0
27	2	2	1	0	0
28	2	2	1	0	0
29	2	2	1	0	0
30	2	2	1	0	0
31	2	2	1	0	0
32	2	2	1	0	0
33	2	2	1	0	0
34	2	2	1	0	0
35	2	2	1	0	0
36	2	2	1	0	0
37	2	2	1	0	0
38	2	2	1	0	0
39	2	2	1	0	0
40	2	2	1	0	0
41	2	2	1	0	0
42	2	2	1	0	0
43	2	2	1	0	0
44	2	2	1	0	0
45	2	2	1	0	0
46	2	2	1	0	0
47	2	2	1	0	0
48	2	2	1	0	0
49	2	2	1	0	0
50	2	2	1	0	0
51	2	2	1	0	0

## ARITHMETICAL INSTRUCTIONS REFINED

MEM-LOC.	STROBE	ACCUMULATOR INSTRUCTIONS DEFINED					
		I/O	WRITE	READ	CLEAR1	SET1	CLEAR2
0	0	0	0	0	0	0	0
1	1	0	0	0	0	0	0
2	1	0	0	0	0	0	0
3	1	0	0	0	0	0	0
4	1	0	0	0	0	0	0
5	1	0	0	0	0	0	0
6	1	0	0	0	0	0	0
7	1	0	0	0	0	0	0
8	1	0	0	0	0	0	0
9	1	0	0	0	0	0	0
10	1	0	0	0	0	0	0
11	1	0	0	0	0	0	0
12	1	0	0	0	0	0	0
13	1	0	0	0	0	0	0
14	1	0	0	0	0	0	0
15	1	0	0	0	0	0	0
16	1	0	0	0	0	0	0
17	1	0	0	0	0	0	0
18	1	1	1	1	0	0	0
19	1	0	0	0	0	0	1
20	1	0	0	0	0	0	0
21	1	1	1	1	0	0	0
22	1	1	1	0	0	0	0
23	1	1	1	0	0	0	0
24	1	0	0	0	0	0	0
25	1	1	1	0	0	0	0
26	1	0	0	0	0	0	0
27	0	0	0	0	0	0	0
28	0	0	0	0	0	0	0
29	0	0	0	0	0	0	0
30	0	0	0	0	0	0	0
31	0	0	0	0	0	0	0
32	0	0	0	0	0	0	1
33	0	0	0	0	0	0	0
34	0	0	0	0	0	0	1
35	0	0	0	0	0	0	1
36	0	0	0	0	0	0	1
37	0	0	0	0	0	0	1
38	0	0	0	0	0	0	1
39	0	0	0	0	0	0	1
40	0	0	0	0	0	0	1
41	0	0	0	0	0	0	1
42	0	0	0	0	0	0	1
43	0	0	0	0	0	0	1
44	0	0	0	0	0	0	1
45	1	0	0	1	0	0	0
46	1	0	1	0	0	0	0
47	1	0	0	0	0	0	0
48	1	0	0	0	0	0	0
49	1	1	0	0	0	0	0
50	1	0	0	0	0	0	0
51	1	1	0	0	0	0	0

## I/O INSTRUCTIONS DEFINED.

MEM-LOC.	SETF	CLEARF	SELECT	BUF	ADDR.	STROBE	I-REG.	ENABLE EDB	ENABLE EAB
0	0	0	0				0		0
1	0	0	0				0		0
2	0	0	0				0		0
3	0	0	0				0		0
4	0	0	0				0		0
5	0	0	0				0		0
6	0	0	0				0		0
7	0	0	0				0		0
8	0	0	0				0		0
9	0	0	0				0		0
10	0	0	0				0		0
11	0	0	0				0		0
12	0	0	0				0		0
13	0	0	0				0		0
14	0	0	0				0		0
15	0	0	0				0		0
16	0	0	0				0		0
17	0	0	0				0		0
18	0	0	0				0		0
19	0	0	0				0		0
20	0	0	0				0		0
21	0	0	0				0		0
22	0	0	0				0		0
23	0	0	0				0		0
24	0	0	0				0		0
25	0	0	0				0		0
26	0	0	0				0		0
27	0	0	0				0		0
28	0	0	0				0		0
29	0	0	0				0		0
30	0	0	0				0		0
31	0	0	0				0		0
32	0	0	0				0		0
33	0	0	0				0		0
34	0	0	0				0		0
35	0	0	0				0		0
36	0	0	0				0		0
37	0	0	0				0		0
38	0	0	0				0		0
39	0	0	0				0		0
40	0	0	0				0		0
41	0	0	0				0		0
42	0	0	0				0		0
43	0	0	0				0		0
44	0	0	0				0		0
45	0	0	0				0		0
46	0	0	0				0		0
47	0	0	0				0		0
48	0	0	0				0		0
49	0	0	0				0		0
50	0	0	0				0		0
51	0	0	0				0		0

OUTPUT-TRANSFER INSTRUCTIONS DEFINED

MEM-LOC.	TRANSFER	INHIBIT-CLOCK	DATA-READY	TRANSFER-CODE	SOURCE
0	0	0	0	0	0
1	0	0	0	0	0
2	0	0	0	0	0
3	0	0	0	0	0
4	0	0	0	0	0
5	0	0	0	0	0
6	0	0	0	0	0
7	0	0	0	0	0
8	0	0	0	0	0
9	0	0	0	0	0
10	0	0	0	0	0
11	0	0	0	0	0
12	0	0	0	0	0
13	0	0	0	0	0
14	0	0	0	0	0
15	0	0	0	0	0
16	0	0	0	0	0
17	0	0	0	0	0
18	0	0	0	0	0
19	0	0	0	0	0
20	0	0	0	0	0
21	0	0	0	0	0
22	0	0	0	0	0
23	0	0	0	0	0
24	0	0	0	0	0
25	0	0	0	0	0
26	0	0	0	0	0
27	1	0	0	0	0
28	1	0	0	0	0
29	1	0	0	0	0
30	1	0	0	0	0
31	1	0	0	0	0
32	0	0	0	0	0
33	0	0	0	0	0
34	1	0	0	0	0
35	1	1	1	1	0
36	1	1	1	1	1
37	1	1	1	1	3
38	1	1	1	1	2
39	1	1	1	1	5
40	1	1	1	1	4
41	1	0	0	0	0
42	1	0	0	0	0
43	1	0	0	0	0
44	1	0	0	0	0
45	0	0	0	0	0
46	0	0	0	0	0
47	0	0	0	0	0
48	0	0	0	0	0
49	0	0	0	0	0
50	0	0	0	0	0
51	0	0	0	0	0

ANNEX 3

Program with coherent integration.

APB STACK

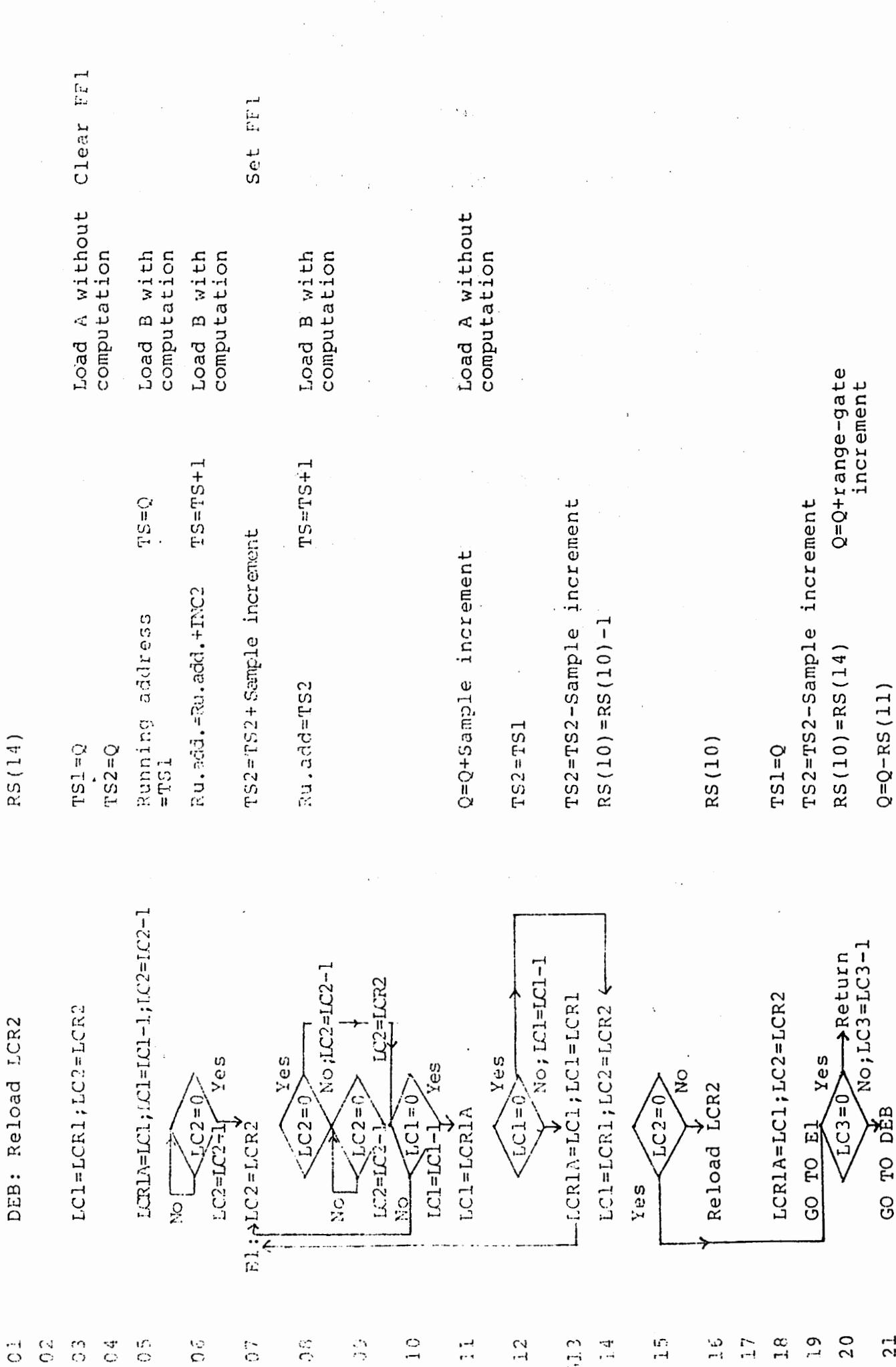
RS (15) No. of points to add - 1  
RS (14) No. of scan / No. of points to add - 1  
RS (13) No. of range gates - 1  
RS (12) Sample increment (Signal + Background + Calibration)  
RS (11) (Sample increment x N0. of scan - 1)  
RS (10) RS (14)  
RS (9) Increment 2 (Sample increment x No. of points to add)  
RS (8) Increment 1  
RS (7) No. of noise samples - 1 AND No. of calibration samples - 1  
RS (6) No. of scan - 1  
RS (5) No. of frequencies  
RS (4) RS (5)  
RS (3) Temporary storage 1  
RS (2) Running address  
RS (1) Temporary storage 2  
RS (0) Free

APM STACK

RS (15) Range-gate increment (No. of scan/No. of points to add)  
RS (14) 1  
RS (0) 1

DATA-I-REGISTER

DATA-I-REG = No. of frequencies x (Range-gate increment x No. of ranges  
+ 2)

ACCARIAPMPROMEMLOCATION

## PROGRAM-INSTRUCTIONS DEFINED

MEM-LOC.	COND-CODE	CODE-B	CODE-A	ADDR.	LC1	LCR1A	LC2	LC3	RELOAD	R-ADDR.
0	56	0	4	0	0	0	0	0	0	0
1	32	6	4	0	0	0	0	0	0	0
2	32	6	4	0	0	0	0	0	0	0
3	32	6	4	0	0	0	0	0	1	18
4	32	6	4	0	0	0	0	0	0	0
5	32	6	4	0	2	0	0	0	0	0
6	57	6	4	53	0	0	0	0	0	0
7	32	6	4	0	0	0	0	0	1	20
8	32	6	4	0	0	0	0	0	0	0
9	32	6	4	0	0	0	0	0	1	18
10	32	6	5	45	0	0	0	0	0	0
11	32	6	4	0	0	0	0	0	1	19
12	32	6	4	0	0	0	0	0	0	0
13	32	5	4	0	2	0	3	0	0	0
14	32	6	4	0	0	0	0	0	0	0
15	32	6	4	0	1	1	1	0	0	0
16	58	4	6	16	0	0	1	0	0	0
17	32	6	4	0	0	0	3	0	0	0
18	58	6	4	20	0	0	1	0	0	0
19	58	4	5	19	0	0	1	0	0	0
20	57	4	5	17	1	0	3	0	0	0
21	32	5	4	0	3	0	0	0	0	0
22	57	5	4	24	1	0	0	0	0	0
23	32	5	5	17	2	1	0	0	0	0
24	32	5	4	0	2	0	3	0	0	0
25	58	5	4	30	0	0	0	0	0	0
26	32	5	4	0	0	0	0	0	1	19
27	32	5	4	0	0	0	0	0	0	0
28	32	5	4	0	0	1	3	0	0	0
29	32	5	5	17	0	0	0	0	0	0
30	60	1	4	0	0	0	0	0	1	0
31	32	6	5	11	0	0	0	0	0	0
32	56	0	4	0	0	0	0	0	1	20
33	56	0	4	0	0	0	0	0	0	0
34	56	0	4	0	0	0	0	0	0	0
35	56	0	4	0	0	0	0	0	0	0
36	56	0	3	0	0	0	0	0	2	0
37	56	0	4	0	0	0	0	0	1	0
38	56	0	4	0	0	0	0	0	0	0
39	56	0	4	0	0	0	0	0	0	0
40	60	0	3	0	0	0	0	0	0	0
41	56	0	4	0	0	0	0	0	0	0
42	56	0	4	0	0	0	0	0	0	0
43	56	0	4	0	0	0	0	0	0	0
44	56	0	5	0	0	0	0	0	0	0
45	32	5	4	10	11	0	0	0	2	0
46	52	5	4	0	0	0	0	0	1	19
47	32	5	4	0	0	0	0	0	0	0
48	32	5	4	0	0	0	0	0	1	18
49	32	6	4	0	0	0	0	0	0	0
50	32	0	10	55	0	0	0	0	0	0
51	32	0	10	55	0	0	0	0	0	0
52	32	5	5	3	0	0	0	0	0	0
53	56	0	4	0	0	0	0	0	0	0
54	32	5	6	0	0	0	0	0	0	0
55	32	5	4	0	0	0	0	0	0	0
56	56	0	4	0	0	2	0	3	0	0
57	57	5	4	0	1	0	0	0	0	0
58	57	5	4	0	1	0	0	0	0	0
59	57	5	5	0	1	0	0	0	0	0
60	56	0	4	0	0	0	0	0	0	0
61	56	0	4	0	0	0	0	0	0	0

## APM-INSTRUCTIONS DEFINED

MEM-LOC.	ALU-SOURCE	ALU-FUNCTION	ALU-DESTIN.	A-ADDR.	B-ADDR.
0	7	5	1	0	0
1	2	4	1	0	0
2	2	4	1	0	0
3	2	4	1	0	0
4	2	4	1	0	0
5	2	4	1	0	0
6	2	4	1	0	0
7	2	4	1	0	0
8	2	4	1	0	0
9	2	4	1	0	0
10	2	4	1	0	0
11	2	4	1	0	0
12	2	4	1	0	0
13	2	4	1	0	0
14	2	4	1	0	0
15	2	4	1	0	0
16	2	4	1	0	0
17	2	4	1	0	0
18	2	4	1	0	0
19	2	4	1	0	0
20	2	4	1	0	0
21	2	4	1	0	0
22	2	4	1	0	0
23	2	4	1	0	0
24	2	4	1	0	0
25	2	4	1	0	0
26	2	4	1	0	0
27	2	4	1	0	0
28	2	4	1	0	0
29	2	4	1	0	0
30	2	4	1	0	0
31	2	4	1	0	0
32	2	4	1	0	0
33	2	4	1	0	0
34	2	4	1	0	0
35	2	4	1	0	0
36	2	4	1	0	0
37	2	4	1	0	0
38	2	4	1	0	0
39	2	4	1	0	0
40	2	4	1	0	0
41	2	4	1	0	0
42	2	4	1	0	0
43	2	4	1	0	0
44	2	4	1	0	0
45	2	4	1	0	0
46	2	4	1	0	0
47	2	4	1	0	0
48	2	4	1	0	0
49	2	4	1	0	0
50	2	4	1	0	0
51	2	4	1	0	0
52	2	4	1	0	0
53	2	4	1	0	0
54	2	4	1	0	0
55	2	4	1	0	0
56	2	4	1	0	0
57	2	4	1	0	0
58	2	4	1	0	0
59	2	4	1	0	0
60	2	4	1	0	0
61	2	4	1	0	0

APB-INSTRUCTIONS DEFINED

ALU-SOURCE ALU-FUNCTION ALU-DESTIN. A-ADDR. B-ADDR. SELECT

MEM-LOC.						
0	7	5	1	0	0	0
1	4	0	3	5	4	0
2	2	4	1	0	0	0
3	4	0	1	4	0	0
4	2	4	1	0	0	0
5	2	4	1	0	0	0
6	1	1	3	8	4	0
7	4	0	1	13	0	0
8	2	4	1	0	0	0
9	4	0	1	15	0	0
10	2	4	1	0	0	0
11	4	0	1	14	0	0
12	2	4	1	0	0	0
13	4	0	1	0	3	0
14	2	4	1	3	3	0
15	4	0	1	3	3	0
16	1	1	3	12	0	0
17	4	0	1	1	9	0
18	2	4	1	0	0	0
19	4	0	1	0	0	0
20	2	4	1	0	0	0
21	0	0	0	12	1	0
22	4	0	3	3	0	0
23	1	1	3	12	0	0
24	2	4	1	8	0	0
25	4	0	1	10	0	0
26	2	4	1	0	0	0
27	2	4	1	0	0	0
28	2	4	1	12	0	0
29	0	0	0	14	1	0
30	4	0	3	10	0	0
31	0	0	0	11	0	0
32	7	7	1	0	0	0
33	7	7	1	0	0	0
34	7	7	1	0	0	0
35	7	7	1	0	0	0
36	7	7	1	0	0	0
37	7	7	1	0	0	0
38	7	7	1	0	0	0
39	7	7	1	0	0	0
40	7	7	1	0	0	0
41	7	7	1	0	0	0
42	7	7	1	0	0	0
43	7	7	1	0	0	0
44	7	7	1	0	0	0
45	2	4	0	7	0	0
46	4	2	0	6	0	0
47	2	4	0	0	0	0
48	4	2	0	0	0	0
49	2	4	0	0	0	0
50	0	0	1	11	0	0
51	7	7	0	8	3	0
52	1	7	0	0	0	0
53	7	7	1	0	0	0
54	2	5	0	12	11	0
55	1	5	0	11	2	0
56	0	5	0	11	2	0
57	0	5	1	11	0	0
58	2	0	0	12	2	0
59	0	0	0	12	2	0
60	0	0	0	12	2	0
61	2	0	1	11	2	0
62	0	0	1	12	2	0

SET THE CRITICAL INSTRUCTIONS DEFINED

MEM-LOC.	ACCUMULATOR INSTRUCTIONS						DEFINED	
	STROBE	I/O	WRITE	READ	CLEAR1	SET1	CLEAR2	SET2
0	0	0	0	0	0	0	0	0
1	0	0	0	0	0	0	0	0
2	0	0	0	0	0	0	0	0
3	0	0	0	0	0	0	0	0
4	0	0	0	0	0	0	0	0
5	0	0	0	0	0	0	0	0
6	0	0	0	0	0	0	0	0
7	0	0	0	0	0	0	0	0
8	0	0	0	0	0	0	0	0
9	0	0	0	0	0	0	0	0
10	0	0	0	0	0	0	0	0
11	0	0	0	0	0	0	0	0
12	0	0	0	0	0	0	0	0
13	0	0	0	0	1	0	0	0
14	0	0	0	0	0	0	0	0
15	1	1	1	0	0	0	0	0
16	1	1	1	0	0	0	0	0
17	0	0	0	0	0	1	0	0
18	1	1	1	0	0	0	0	0
19	1	1	1	0	0	0	0	0
20	0	0	0	0	0	0	0	0
21	0	0	0	0	0	0	0	0
22	0	0	0	0	0	0	0	0
23	0	0	0	0	0	0	0	0
24	0	0	0	0	0	0	0	0
25	0	0	0	0	0	0	0	0
26	0	0	0	0	0	0	0	0
27	0	0	0	0	0	0	0	0
28	0	0	0	0	0	0	0	0
29	0	0	0	0	0	0	0	0
30	0	0	0	0	0	0	0	0
31	0	0	0	0	0	0	0	0
32	0	0	0	0	0	0	0	0
33	0	0	0	0	0	0	0	0
34	0	0	0	0	0	0	0	0
35	0	0	0	0	0	0	0	0
36	0	0	0	0	0	0	0	0
37	0	0	0	0	0	0	0	0
38	0	0	0	0	0	0	0	0
39	0	0	0	0	0	0	0	0
40	0	0	0	0	0	0	0	0
41	0	0	0	0	0	0	0	0
42	0	0	0	0	0	0	0	0
43	0	0	0	0	0	0	0	0
44	0	0	0	0	0	0	1	0
45	0	0	0	0	0	0	0	0
46	0	0	0	0	0	0	0	0
47	0	0	0	0	0	0	0	0
48	0	0	0	0	0	0	0	0
49	0	0	0	0	0	0	0	0
50	0	0	0	0	0	0	0	0
51	0	0	0	0	0	0	0	0
52	0	0	0	0	0	0	0	0
53	1	1	1	0	0	0	0	0
54	0	0	0	0	0	0	0	1
55	0	0	0	0	0	0	0	0
56	1	0	0	0	1	0	0	0
57	1	0	0	1	0	0	0	0
58	1	0	0	0	0	0	0	0
59	1	1	0	0	0	0	0	0
60	1	1	0	0	0	0	1	0
61	1	1	0	0	0	0	0	0
62	1	1	0	0	0	0	0	0

#### 170 INSTRUCTIONS DEFINED

MEM-LOC.	SETF	CLEARF	SELECT	SBUF	ADDR.	STROBE	I-REG.	ENABLE	EDB	ENABLE	EAB
0	0	0	0	0		0		0		0	
1	0	0	0	0		0		0		0	
2	0	0	0	0		0		0		0	
3	0	0	0	0		0		0		0	
4	0	0	0	0		0		0		0	
5	0	0	0	0		0		0		0	
6	0	0	0	0		0		0		0	
7	0	0	0	0		0		0		0	
8	0	0	0	0		0		0		0	
9	0	0	0	0		0		0		0	
10	0	0	0	0		0		0		0	
11	0	0	0	0		0		0		0	
12	0	0	0	0		0		0		0	
13	0	0	0	0		0		0		0	
14	0	0	0	0		0		0		0	
15	0	0	0	0		0		0		0	
16	0	0	0	0		0		0		0	
17	0	0	0	0		0		0		0	
18	0	0	0	0		0		0		0	
19	0	0	0	0		0		0		0	
20	0	0	0	0		0		0		0	
21	0	0	0	0		0		0		0	
22	0	0	0	0		0		0		0	
23	0	0	0	0		0		0		0	
24	0	0	0	0		0		0		0	
25	0	0	0	0		0		0		0	
26	0	0	0	0		0		0		0	
27	0	0	0	0		0		0		0	
28	0	0	0	0		0		0		0	
29	0	0	0	0		0		0		0	
30	0	0	0	0		0		0		0	
31	0	0	0	0		0		0		0	
32	0	0	0	0		0		0		0	
33	0	0	0	0		0		0		0	
34	0	0	0	0		0		0		0	
35	0	0	0	0		0		0		0	
36	0	0	0	0		0		0		0	
37	0	0	0	0		0		0		0	
38	0	0	0	0		0		0		0	
39	0	0	0	0		0		0		0	
40	0	0	0	0		0		0		0	
41	0	0	0	0		0		0		0	
42	0	0	0	0		0		0		0	
43	0	0	0	0		0		0		0	
44	0	0	0	0		0		0		0	
45	0	0	0	0		0		0		0	
46	0	0	0	0		0		0		0	
47	0	0	0	0		0		0		0	
48	0	0	0	0		0		0		0	
49	0	0	0	0		0		0		0	
50	0	0	0	0		0		0		0	
51	0	0	0	0		0		0		0	
52	0	0	0	0		0		0		0	
53	0	0	0	0		0		0		0	
54	0	0	0	0		0		0		0	
55	0	0	0	0		0		0		0	
56	0	0	0	0		0		0		0	
57	0	0	0	0		0		0		0	
58	0	0	0	0		0		0		0	
59	0	0	0	0		0		0		0	
60	0	0	0	0		0		0		0	
61	0	0	0	0		0		0		0	
62	0	0	0	0		0		0		0	

## OUTPUT-TRANSFER INSTRUCTIONS DEFINED

28.

MEM-LOC.	TRANSFER	INHIBIT	CLOCK	DATA-READY	TRANSFER-CODE	SOURCE
0	0		0	0	0	0
1	0		0	0	0	0
2	0		0	0	0	0
3	0		0	0	0	0
4	0		0	0	0	0
5	0		0	0	0	0
6	0		0	0	0	0
7	0		0	0	0	0
8	0		0	0	0	0
9	0		0	0	0	0
10	0		0	0	0	0
11	0		0	0	0	0
12	0		0	0	0	0
13	0		0	0	0	0
14	0		0	0	0	0
15	0		0	0	0	0
16	0		0	0	0	0
17	0		0	0	0	0
18	0		0	0	0	0
19	0		0	0	0	0
20	0		0	0	0	0
21	0		0	0	0	0
22	0		0	0	0	0
23	0		0	0	0	0
24	0		0	0	0	0
25	0		0	0	0	0
26	0		0	0	0	0
27	0		0	0	0	0
28	0		0	0	0	0
29	0		0	0	0	0
30	0		0	0	0	0
31	0		0	0	0	0
32	0		0	0	0	0
33	0		0	0	0	0
34	1		0	0	0	0
35	1		1	1	1	1
36	1		1	1	1	3
37	1		1	1	1	2
38	1		1	1	1	5
39	1		1	1	1	4
40	1		1	1	1	0
41	1		0	0	0	0
42	1		0	0	0	0
43	1		0	0	0	0
44	1		0	0	0	0
45	0		0	0	0	0
46	0		0	0	0	0
47	0		0	0	0	0
48	0		0	0	0	0
49	0		0	0	0	0
50	0		0	0	0	0
51	0		0	0	0	0
52	0		0	0	0	0
53	0		0	0	0	0
54	0		0	0	0	0
55	0		0	0	0	0
56	0		0	0	0	0
57	0		0	0	0	0
58	0		0	0	0	0
59	0		0	0	0	0
60	0		0	0	0	0
61	0		0	0	0	0
62	0		0	0	0	0
63	0		0	0	0	0

EISCAT publications

F. du Castel, O. Holt, B. Hultqvist, H. Kohl and M. Tiuri:  
A European Incoherent Scatter Facility in the Auroral Zone (EISCAT).  
A Feasibility Study ("The Green Report") June 1971. (Out of print).

O. Bratteng and A. Haug:

Model Ionosphere at High Latitude, EISCAT Feasibility Study, Report  
No. 9.  
The Auroral Observatory, Tromsö July 1971. (Out of print).

A European Incoherent Scatter Facility in the Auroral Zone, UHF  
System and Organization ("The Yellow Report"), June 1974.

EISCAT Annual Report 1976. (Out of print).

P.S. Kildal and T. Hagfors:

Balance between investment in reflector and feed in the VHF cylindrical  
antenna.

EISCAT Technical Notes No. 77/1, 1977.

T. Hagfors:

Least mean square fitting of data to physical models.  
EISCAT Technical Notes No. 78/2, 1978.

T. Hagfors:

The effect of ice on an antenna reflector.  
EISCAT Technical Notes No. 78/3, 1978.

T. Hagfors:

The bandwidth of a linear phased array with stepped delay corrections.  
EISCAT Technical Notes No. 78/4, 1978.

Data Group meeting in Kiruna, Sweden, 18-20 Jan. 1978  
EISCAT Meetings No. 78/1, 1978

EISCAT Annual Report 1977

H-J. Alker:

Measurement principles in the EISCAT system;  
EISCAT Technical Notes No. 78/5, 1978

EISCAT Data Group meeting in Tromsö, Norway 30-31 May, 1978  
EISCAT Meetings No. 78/2, 1978.

P-S. Kildal:

Discrete phase steering by permuting precut phase cables.  
EISCAT Technical Notes No. 78/6, 1978

EISCAT UHF antenna acceptance test.

EISCAT Technical Notes No. 78/7, 1978.

P-S. Kildal:

Feeder elements for the EISCAT VHF parabolic cylinder antenna.  
EISCAT Technical Notes No. 78/8, 1978.

H-J. Alker:

Program CORRSIM: System for program development and software simulation of EISCAT digital correlator, User's Manual.  
EISCAT Technical Notes No. 79/9, 1979.

H-J. Alker:

Instruction manual for EISCAT digital correlator.  
EISCAT Technical Notes No. 79/10, 1979

H-J. Alker:

A programmable correlator module for the EISCAT radar system.  
EISCAT Technical Notes No. 79/11, 1979.

T. Ho and H-J. Alker:

Scientific programming of the EISCAT digital correlator.  
EISCAT Technical Notes No. 79/12, 1979.

S. Westerlund (editor):

Proceedings EISCAT Annual Review Meeting 1969. Part I and II,  
Abisko, Sweden, 12-16 March 1979.

EISCAT Meetings No. 79/3, 1979.

J. Murdin:

EISCAT UHF Geometry.

EISCAT Technical Notes No. 79/13, 1979.

T. Hagfors:

Transmitter Polarization Control in the EISCAT UHF System.

EISCAT Technical Notes No. 79/14, 1979.

B. Törustad:

A description of the assembly language for the EISCAT digital correlator.

EISCAT Technical Notes No. 79/15, 1979.

J. Murdin:

Errors in incoherent scatter radar measurements.

EISCAT Technical Notes No. 79/16, 1979.

EISCAT Digital Correlator. TEST MANUAL.

EISCAT Technical Notes No. 79/17, 1979.

G. Lejeune:

A program library for incoherent scatter calculation.

EISCAT Technical Notes No. 79/18, 1979.

K. Folkestad:

Lectures for EISCAT Personnel, Volume I

EISCAT Technical Notes No. 79/19, 1979.

Svein A. Kvalvik:

Correlator Buffer-Memory for the EISCAT Radar system

EISCAT Technical Notes No. 80/20.

P-S. Kildal:

EISCAT VHF Antenna Tests

EISCAT Technical Notes No. 80/21

J. Armstrong:

EISCAT Experiment Preparation Manual

EISCAT Technical Notes No. 80/22

A. Farmer:

EISCAT Data Gathering and Dissemination

EISCAT Technical Note 80/23

Terrance Ho and Hans-Jørgen Alker:

Scientific Programming of the EISCAT Digital Correlator (Revised)

EISCAT Technical Note 81/24

Terrance Ho:

Programs Corrsim, Corrtest: System for Program Development and Software Simulation of EISCAT Digital Correlator, User's manual.

EISCAT Technical Note 81/25

Terrance Ho:

Instruction Manual for EISCAT Digital Correlator (Revised).

EISCAT Technical Note 81/26

Terrance Ho:

Standard Subroutines and Programs for EISCAT Digital Correlator.

EISCAT Technical Note 81/27

Terrance Ho:

Pocket Manual for Programming the EISCAT Digital Correlator.

EISCAT Technical Note 81/28

K. Folkestad:

Lectures for EISCAT Personnel, Volume II.

EISCAT Technical Note 81/29

M, Lehtinen och Anna-Liisa Turunen:

EISCAT UHF antenna direction calibration

EISCAT Technical Note 81/30

K. Folkestad:

Use of the EISCAT Radar as a supplement to rocket measurements.  
EISCAT Technical Note 81/31

T. Turunen, T Mustonen and P J S Williams:

EISCAT UHF RECEIVERS: Report and Recommendations  
EISCAT Technical Note 81/32

Phil Williams:

Polarisers in the EISCAT System  
EISCAT Technical Note 81/33

R. Gras:

THE EISCAT CORRELATOR  
EISCAT Technical Note 82/34